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3.021J / 1.021J / 10.333J / 18.361J / 22.00J Introduction to Modeling and Simulation  
Spring 2008

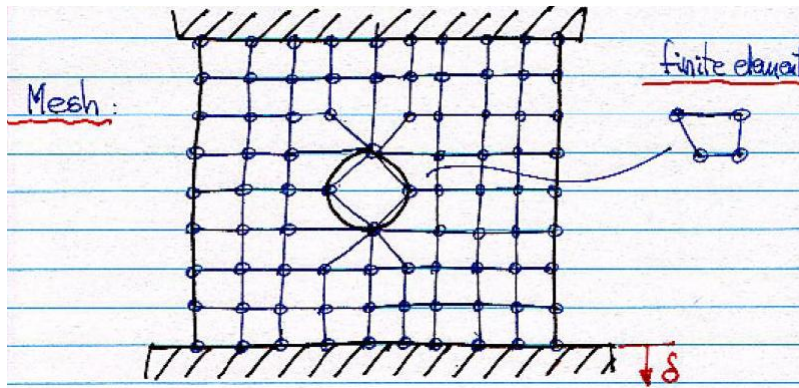
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## Lecture 6 - The Finite Element Method

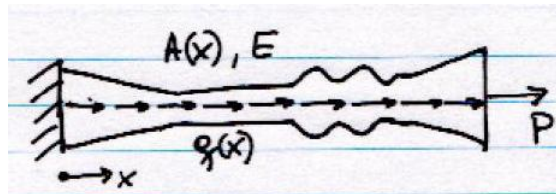
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- Overcome limitations of Ritz:
- Simple basic functions (low order polynomials)
- Basic functions supported in subdomains (finite elements)
- Basic functions constructed to provide interpolant of approximate solution.
- Undetermined parameters represent values of dependent variables (solution) at subdomain boundaries.



### Model Problem

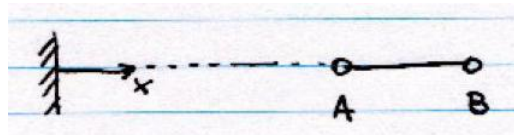


$$\frac{d}{dx} \left( EA(x) \frac{du}{dx} \right) + q(x) = 0 \quad 0 < x < L$$

Boundary Conditions: “ $u$ ” specified:  $u(0) = 0$

“ $EA \frac{du}{dx}$ ” specified:  $EA \frac{du}{dx} \Big|_L = P$

### Formulation of generic element



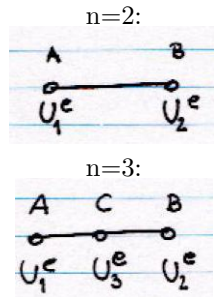
$$\Omega^e : (x_A, x_B)$$

$$(x_1^e, x_2^e)$$

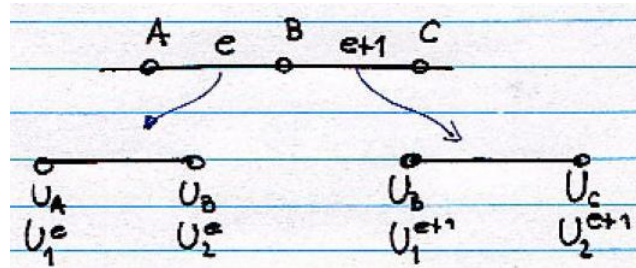
Seek variational approximation in this domain:

$$u(x) \approx u_e(x) = \sum_{i=1}^n \phi_i^e(x) U_i^e \quad x_A < x < x_B$$

n: number of "nodes" in element



Note: choosing undetermined parameters for the values of the solution at the nodes enforces continuity of the solution across elements.



This imposes conditions on  $\phi_i^e$

$$u_e(x_j) = \sum_{i=1}^n \phi_i^e(x_j) U_i^e = U_j^e$$

$$= \phi_1^e(x_j) U_1^e + \dots + \phi_j^e(x_j) U_j^e + \dots + \phi_n^e(x_j) U_n^e$$

$$= 0 + 0 + 1(U_j^e) + 0 + 0$$

or  $\phi_i^e(x_j) = \delta_{ij}$

$\implies$  Lagrange polynomials

$$\phi_j^e = \prod_{k=1, k \neq j}^n \frac{x - x_k^e}{x_j^e - x_k^e}$$

$$\phi_j^e(x) = \frac{x - x_1}{x_j - x_1} \dots \frac{x - x_{j-1}}{x_j - x_{j-1}} \left[ \quad \right] \frac{x - x_{j+1}}{x_j - x_{j+1}} \dots \frac{x - x_n}{x_j - x_n}$$

$$\phi_j^e(x_i) = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases} = \delta_{ij}$$

Another important property that  $\phi_i^e$  must satisfy is to allow for the representation of constant solutions exactly:

$$\begin{aligned} u(x) &= C = \sum_{i=1}^n \phi_i^e(x) U_i^e \quad x_A < x < x_B \\ &= \sum_{i=1}^n \phi_i^e(x) C = C \underbrace{\sum_{i=1}^n \phi_i^e}_{1} \\ &\quad \sum \phi_i^e(x) = 1 \end{aligned}$$

## Examples

$$\phi_j^e(x) = \prod_{k=1, k \neq j}^2 \frac{x - x_k}{x_j - x_k}$$

$$n = 2 :$$

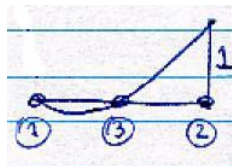
$$\phi_1^e = \frac{x - x_2}{x_1 - x_2} \quad \phi_2^e = \frac{x - x_1}{x_2 - x_1}$$

$$n = 3 :$$

$$\phi_1^e = \frac{(x - x_2)(x - x_3)}{(x_1 - x_2)(x_1 - x_3)}$$



$$\phi_2^e = \frac{(x - x_1)(x - x_3)}{(x_2 - x_1)(x_2 - x_3)}$$

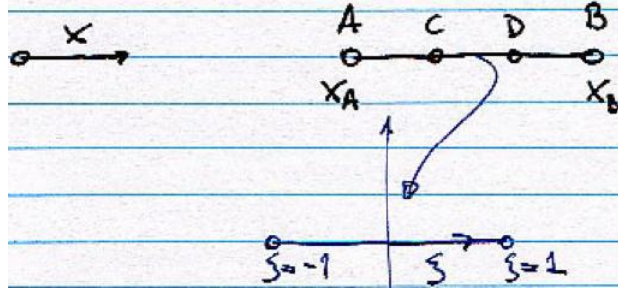


$$\phi_3^e = \frac{(x - x_1)(x - x_2)}{(x_3 - x_1)(x_3 - x_2)}$$



## Natural coordinate system

The functions look simpler when expressed in terms of the local coordinate system:



The translation from “ $\xi$ ” to “ $x$ ” is

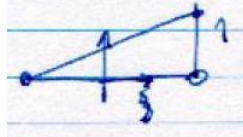
$$x = \frac{1-\xi}{2}x_A + \frac{1+\xi}{2}x_B$$

$n = 2$ :

$$\begin{aligned}\phi_1 &= \frac{x - x_B}{x_A - x_B} = \frac{1}{x_A - x_B} \left[ \frac{x_A + x_B}{2} + \frac{x_B - x_A}{2}\xi - x_B \right] \\ &= \frac{1}{x_A - x_B} \left[ \frac{x_A - x_B}{2} - \frac{x_A - x_B}{2}\xi \right] \\ &= \frac{1}{2}(1 - \xi)\end{aligned}$$

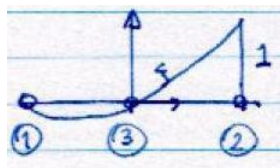


$$\phi_2 = \frac{1}{2}(1 + \xi)$$

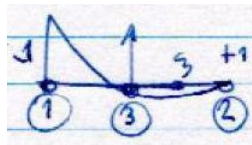


$n = 3 :$

$$\phi_1 = \frac{1}{2}\xi(1 + \xi)$$



$$\phi_2 = \frac{1}{2}\xi(1 - \xi)$$



$$\phi_3 = (1 - \xi)(1 + \xi)$$

